

Static Analysis by Policy Iteration on Relational Domains

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Static Analysis

Static Analysis

- (1) Parse C code, produce semantic equations
- (2) Provide abstractions of operators and equations
- (3) Solve the abstract equations (**costly step!**)

0	<code>i = 150; j = 175;</code>	M_0	$=$	<i>context_initialization</i>
1	<code>while (j >= 100){</code>	M_1	$=$	<i>Assign</i> $i \leftarrow 150, j \leftarrow 175(M_0)$
2	<code> i++;</code>	M_2	$=$	$(M_1 \sqcup M_6) \sqcap (j \geq 100)$
3	<code> if (j <= i){</code>	M_3	$=$	<i>Assign</i> $i \leftarrow i+1(M_2)$
4	<code> i = i - 1;</code>	M_4	$=$	$M_3 \sqcap (j \leq i)$
5	<code> j = j - 2;</code>	M_5	$=$	<i>Assign</i> $i \leftarrow i-1, j \leftarrow j-2(M_4)$
6	<code> }</code>	M_6	$=$	$(M_5 \sqcap (j > i)) \sqcup M_7$
7	<code>}</code>	M_7	$=$	$(M_2 \sqcup M_8) \sqcap (j < 100)$

Static Analysis by Abstract Interpretation

- D_a and D_c are complete lattices
- F_c is the best abstraction for F_a

$$\begin{array}{ccc}
 \text{Concrete Domain} & (D_c, \sqsubseteq_c) & \xrightarrow{F_c} & (D_c, \sqsubseteq_c) \\
 & \alpha \downarrow \uparrow \gamma & & \alpha \downarrow \uparrow \gamma \\
 \text{Abstract Domain} & (D_a, \sqsubseteq_a) & \xrightarrow{F_a} & (D_a, \sqsubseteq_a)
 \end{array}$$

Galois connection [Cousot and Cousot:77]

$$\begin{aligned}
 \alpha(x) \sqsubseteq_a y &\iff x \sqsubseteq_c \gamma(y) \\
 \implies \gamma(\text{lfp}(F_a)) &\text{ is an overapproximation of } \text{lfp}(F_c)
 \end{aligned}$$

Linear Relational Abstract Domains 1/2

Program variables $x_i \in \mathbb{R}$ ($1 \leq i \leq n$)

Zone Abstract Domain [Mine:01]

- Vector of intervals representing bounds for $x_i - x_j$, $\forall i, j$.
- $\gamma([0, 100], [0, 10], [-10, 5]) = \{(i, j) \mid 0 \leq i \leq 100, 0 \leq j \leq 10, -10 \leq i - j \leq 5\}$

TCM Domain [Manna : 05]

- Parametrized by a set of vectors called $TCM = \{e_1, \dots, e_n\}$ which is **fixed apriori**
- Represented as a vector, each coordinate keeps track of the upper bound of $e_i \cdot (x_1, \dots, x_n)^T$
- For the TCM $\{(1, 0), (0, -1), (2, 1)\}$,
 $\gamma(5, 10, 3) = \{(i, j) \mid i \leq 5, j \geq 10, 2i + j \leq 3\}$

Closure

Two different elements may have the same concretization

Example

$$\gamma(0 \leq i \leq 100, 0 \leq j \leq 10, -10 \leq i - j \leq \infty) = \gamma(0 \leq i \leq 100, 0 \leq j \leq 10, -10 \leq i - j \leq 100)$$

Closure

- $a \equiv b$ iff $\gamma(a) = \gamma(b)$.
- $\text{Closure}(a) = a^* = \sqsubseteq$ -minimal element of eqv class of a
- $\text{Closure}([0, 100], [0, 10], [-10, \infty]) = ([0, 100], [0, 10], [-10, 100])$
- *Tightest bound* for each constraint.

Kleene Iteration technique

Principle

- Iteration 0 : $M_0^0 = M_1^0 = \dots = M_p^0 = \perp$
- $k + 1$ Iteration :
 $(M_0^{k+1}, \dots, M_p^{k+1}) = (M_0^k, \dots, M_p^k) \cup F(M_0^k, \dots, M_p^k)$
- To ensure convergence, after some iterations replace \cup by Widening operator ∇

Problems

- Closure and Widening are **incompatible**
- Widening \implies **Loss of Relations !!!**

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Plan

- 1 Introduction
 - Linear Relational Domains
 - Kleene Iteration
- 2 Policy Iteration
 - Policy Selection
 - Algorithmique Issues
- 3 Experimental Results
- 4 Conclusion

Policy Iteration

Express a monotone map F as an infimum of monotone maps g_1, \dots, g_n (called *policies*) over a complete lattice L .

Selection Property

F satisfies the selection property if

- (1) $F(x) = (\inf \{g_1(x), g_2(x), \dots, g_n(x)\})^*$
- (2) $\forall x \exists g F(x) = g(x)$

Theorem

If F satisfies the selection property then the least fixed point of F (denoted by F^-) is given by $F^- = \inf \{(g_1^-)^*, (g_2^-)^*, \dots, (g_n^-)^*\}$

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Algorithm

```

 $k \leftarrow 1, g_1 \leftarrow \text{initial\_policy}(\mathcal{G})$ 
while true do
   $x_k \leftarrow (g_k^-)^*$ 
  if  $x_k = F(x_k)$  then
    return  $x_k$ 
  else
    find  $g$  such that  $F(x_k) = g(x_k)$ 
     $k \leftarrow k + 1, g_k \leftarrow g$ 
  end if
end while

```

Theorem

- Algorithm returns a fixed point of F
- lfps of the successive policies decrease. $(g_{k+1}^-)^* \sqsubset (g_k^-)^*$
- If F is *NonExpansive* ($\|F(x) - F(y)\|_\infty \leq \|x - y\|_\infty$) then algorithm returns lfp of F (CAV:05)

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Finding a Policy Selection

Intersection Policy

- Intervals: $[a, b] \sqcap_{Pol} [c, d] = \inf\{[a, b], [a, d], [c, b], [c, d]\}$
- For Zones, extend to vector of intervals.
- Finitely many policies and selection property is satisfied.

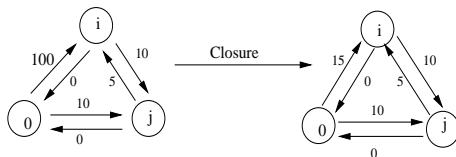
Example

$$([1, 2], [a, b]) \sqcap ([c, d], [3, 4]) = \inf\left\{ \begin{array}{l} ([1, 2], [a, b]), \\ ([c, 2], [a, b]), \\ \dots \\ ([1, 2], [3, 4]), \\ \dots \\ ([c, d], [3, 4]) \end{array} \right\}$$

Closure Policy

Zones \iff Weighted directed graph

- x_1, \dots, x_n form the nodes
- $x_j \xrightarrow{c} x_i$ iff $x_i - x_j \leq c$



Closure

- c^* = shortest path from x_j to x_i in the graph.
- $c^* = \inf(\mathcal{P}_{ij})$ where
 \mathcal{P}_{ij} = Set of weights of all paths from i to j
- Policy = Weight of particular path from i to j
- Extend to all edges

Policy Selection for TCMS

- **Intersection**

$$(e.X^T \leq c_1) \wedge (e.X^T \leq c_2) = (e.X^T \leq \text{inf}(c_1, c_2)).$$

- **Closure**

- Finding *tightest bound* for every vector e in the TCM.
- Amounts to solving the Linear Program :
 $\text{Sup } e.X^T$ subject to $\forall i e_i.X^T \leq c_i$
- Dual: $\text{Inf } \lambda^T c$ subject to $e_1.\lambda_1 + \dots + e_n.\lambda_n = e$
- Solution at extreme point
- Closure = $\text{Inf}(\text{Set of values at all extreme points})$

Algorithmic Issues

lfp of a policy

- Apply policy selection to meet and closure operations of F .
- Each policy g is now convex
- $g^- = \inf\{x | g(x) \sqsubseteq x\}$
- Express $g(x) \sqsubseteq x$ as a set of linear constraints
- Solve using Linear Programming.

Initial Policy Heuristic

- Intersection :
 - Choose constant as opposed to ∞ or variable.
 - Initial Policy for $[a, 10] \sqcap [4, \infty]$ is $[4, 10]$
- Closure :
 - Choose Identity policy ie length 1 path.

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Benchmarks

```
/* test1 */
i = 1; j = 10;
while (i <= j){
    i = i + 2; j = j - 1;
}

/* test2 */
i = 150 ; j = 175;
while (j >= 100){
    i++;
    if( j - i <= 0 ){
        j = j - 2; i = i - 1;
    }
}

/* test3 */
i = 150; j = 175;
while ( 100 <= j && j <= 300){
    i++;
    if( j <= i ){
        j = j - 2; i = i - 1;
    }
}
```

```
/* test4 */
i = 0 ; j = -100;
while (i <= 100){
    i = i + 1;
    while ( j <= 19 ){
        j = i + j;
    }
}
```

```
/* ex5 */
i = 0; j = 100;
k = 1000; l = 10000;
m = 100000;
while (i < 1000)
    i = i+1;
while (j < 1000)
    j = j+k;
while (k > 100)
    k = k-j;
while (l > 1000)
    l = l+k;
while (m > 1)
    m = m-l;
```

Comparing the invariants computed

Programme	Pol + zones	Oct. (A.Miné)	TCMs oct (LPInv)
test1	$\left\{ \begin{array}{l} 1 \leq i \leq 12 \\ 0 \leq j \leq 10 \\ -3 \leq j - i \leq -1 \end{array} \right.$	$\left\{ \begin{array}{l} 6 \leq i \leq 12 \\ \frac{9}{2} \leq j \leq 10 \\ -3 \leq j - i \leq -1 \end{array} \right.$	$\left\{ \begin{array}{l} 6 \leq i \leq 13 \\ 4 \leq j \leq 10 \\ -3 \leq j - i \leq -1 \end{array} \right.$
test2	$\left\{ \begin{array}{l} 150 \leq i \leq 174 \\ 98 \leq j \leq 99 \\ -76 \leq j - i \leq -51 \end{array} \right.$	$\left\{ \begin{array}{l} 150 \leq i \\ 98 \leq j \leq 99 \\ j - i \leq -51 \end{array} \right.$	$\left\{ \begin{array}{l} 150 \leq i \\ j \leq 99 \end{array} \right.$
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test4	$\left\{ \begin{array}{l} i = 101 \\ 1 \leq j \\ -100 \leq j - i \end{array} \right.$	$\left\{ \begin{array}{l} 101 \leq i \leq 120 \\ 1 \leq j \leq 139 \\ -100 \leq j - i \leq 19 \end{array} \right.$	$\left\{ 101 \leq i \right.$
ex5	$\left\{ \begin{array}{l} i = 1000 \\ 1000 \leq j \\ k \leq 100 \\ l \leq 1000 \\ m \leq 1 \\ k - i \leq -900 \\ l - i \leq 0 \\ m - i \leq -999 \\ k - j \leq -99 \\ l - j \leq 0 \\ m - j \leq -999 \end{array} \right.$	$\left\{ \begin{array}{l} i = 1000 \\ 1000 \leq j \leq 1999 \\ -1898 \leq k \leq -1 \\ -897 \leq l \leq 1000 \\ m \leq 1 \\ 0 \leq j - i \leq 999 \\ -2898 \leq k - i \leq -1001 \\ -3897 \leq k - j \leq -1001 \\ -1897 \leq l - i \leq 0 \\ -2896 \leq l - j \leq 0 \\ 1001 \leq l - k \leq 2898 \\ m - i \leq -999 \\ m - j \leq -999 \\ m - k \leq 1899 \\ m - l \leq 898 \end{array} \right.$	$\left\{ \begin{array}{l} i = 1000 \\ 1000 \leq j \leq 1999 \\ k \leq -1 \\ l \leq 1000 \\ m \leq 1 \\ 1001 \leq l - k \end{array} \right.$

Experimental Results

Elementary Operations and Iterations

Program	Elem op Pol	Elem op Oct	Elem op TCM	Iter Pol	Iter Oct	Iter TCM
test1	20	1132	14014	2	7	6
test3	34	1364	62348	1	12	16
test4	68	906	50940	3	4	16
ex5	392	49370	3.10'	1	23	20

GLPK calls

Program	no GLPK Pol	Closure oct.(asgn)	no GLPK TCM
test1	113	138(14)	88(11.14/1.28)
test3	96	333(16)	282(14/1.13)
test4	124	220(13)	302(11.75/1.20)
ex5	659	394(24)	3.10'

Conclusion

- Novel method for computing the fixed point in Linear relational domains
 - No widening used
 - lfp of each policy obtained using Linear Programming.
- Experimental Results
 - Fewer iterations and elementary operations required
 - Precise fixed points even when compared to more informative domains.
 - Hope for better results even with Policy Iteration on TCMs and large examples
- Future Work
 - Gaurenteedly finding the lfp by policy iteration.
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Thank You

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